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AJP 2/14/07

Serial No. 10/528,012

## I. AMENDMENTS

### Amendments to the Claims:

This listing of all pending claims (including withdrawn claims) will replace all prior versions, and listings, of claims in the application. Cancelled and not entered claims are indicated with claim number and status only. The claims show added text with underlining and deleted text with ~~striketrough~~. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

### Listing of Claims:

1. (Currently Amended) A robot toy, comprising:
  - a control unit formed by a movable leg of the robot toy,
  - a clutch to transmit motor power; and
  - a switch; wherein:
    - a four section link including a link, a frame that faces the link, and two swinging links that face each other;
    - a first toy component arranged on the link; and
    - a second toy component arranged on one of the two swinging links that face each other; wherein
      - the clutch is engaged by moving the control unit to change the form of the toy robot, and the motor power is transmitted so that a part of the robot toy conducts at least one among up and down movement, rotating movement, or opening and closing movement, and
      - the switch is switched by moving the control unit, and at least one among number of revolutions of the motor, luminescent color in the robot toy, or sound production, is changed before and after the form change,
    - the one of the two swinging links extends to an opposite side with respect to the frame and a tip thereof rotatably and swingably engages with a rotation disk at an eccentric position, and
    - the first and second toy components are rotated and perform opening and closing movements relative to each other by rotating the rotating disk, before or after the form change.
2. (Previously Presented) The robot toy as claimed in claim 1, wherein a standing posture form and a forward bent posture form are taken by the robot toy according to movement of the control unit.